

## **EEEQ414 Control Systems Engineering B**

**60 hrs. 1.25 units**

**Bachelor of Engineering in Electrical & Electronic Engineering.**

Lecturer: Mr. Benard Mumo Makaa ([www.benardmakaa.com](http://www.benardmakaa.com))

### **Course Outline**

#### **Main Textbook**

Norman S. Nise, (2015) Control Systems Engineering, Wiley.

#### **Reference Textbooks**

1. Norman S. Nise, (2015) Control Systems Engineering, Wiley.
2. Distefano J. J, Stubberud A.R., & Williams I.J (2013), Feedback and Control Systems; Theory and Problems (Schaum's Outline Series), McGraw-Hill.
3. Ogata K. (2016), Modern Control Engineering, Prentice Hall.
4. Kuo, B.C, & Farid G. (2017), Automatic Control Systems, Wiley.
5. Gene F., (2014), Feedback Control of Dynamic Systems, Prentice Hall.

#### **Week 1-Week 4**

---

#### **CAT 1, LAB 1, Assignment 1**

##### **A. Compensation of feedback control systems:**

- Introduction to compensation.
- Reasons for compensation.
- Improving System Performance.

##### **B. Types of compensation:**

- Lag Compensation
- Lead Compensation
- Lag-Lead Compensation.

## **Week 5-Week 10**

---

### **CAT II, LAB II, Assignment 2**

#### **C. Approaches to compensation:**

##### **Dynamic compensation: Design by Root Locus and Frequency Response.**

- Proportional (P) and Integral (I) controllers.
- Proportional and Differential (D) controllers.
- Proportional Integral and Differential compensation (PID) controllers;
- Dynamic compensation and system simulation using operational amplifiers.

#### **D. Cascade compensation networks:**

- System simulation using amplifiers.
- System compensation using phase-lead lag networks.

## **Week 11**

---

#### **E. Public/Guest Lecture-Industrial Visit**