

## Lecture 13: Bode plots for systems

- we have now established the basic building blocks for constructing a Bode plot to represent the frequency response of a system. Each of these elements can be sketched rapidly and accurately using high, low and intermediate frequency asymptotes, and a few key points which define the “departure” of the actual curve from the asymptotes.
- then, as shown in the previous lecture, the Bode plot for a complete system, whose transfer function is the *product* of a number of elementary factors, may be found simply by adding the contributions of each element.

- for example, consider a system with the following transfer function:

$$G(s) = \frac{100(s+2)}{s[s^2 + 4s + 100]} \quad (13.1)$$

- which, in ‘Bode form’:

$$G(s) = \frac{2\left(\frac{s}{2} + 1\right)}{s \left[ \left(\frac{s}{10}\right)^2 + 2(0.2)\left(\frac{s}{10}\right) + 1 \right]} \quad (13.2)$$

- we can now draw the asymptotes, and the departure from these asymptotes, for each of the factors:

1.  $2/s$  - pole at the origin

Note that it is convenient to combine the Bode gain and free- $s$  factors into one factor. The amplitude curve is a straight line of slope  $-1 \text{ dec/dec}$ . The amplitude of  $2/j\omega$  is unity when  $\omega = 2 \text{ rad/s}$ ; hence the straight line passes through the point  $\omega = 2, A(\omega) = 1$ . The phase of  $2/j\omega$  is  $\varphi(\omega) = -90^\circ$  for all frequencies.

2.  $(s/2 + 1)$  - first order lead

This factor has a low-frequency amplitude asymptote  $A(\omega) = 1$  (i.e.,  $Lm = 0$ ), a corner frequency of  $\omega = 2 \text{ rad/s}$ , and a high-frequency asymptote with a slope of  $+1 \text{ dec/dec}$ . The mid-frequency phase asymptote passes through the point  $\omega = 2, \varphi(\omega) = +45^\circ$ .

3.  $\left[ (s/10)^2 + 2(0.2)(s/10) + 1 \right]^{-1}$  - 2<sup>nd</sup> order lag

In writing the 2<sup>nd</sup> order factor in this way, we identify the corner frequency (the undamped natural frequency) as  $10 \text{ rad/s}$  and the damping ratio  $\zeta = 0.2$ . The low-frequency amplitude asymptote is  $A(\omega) = 1$ , while the high-frequency asymptote is a line of slope  $-2 \text{ dec/dec}$ , passing through  $\omega = 10, A(\omega) = 1$ .

For a damping ratio as small as  $0.2$ , the departure from the asymptote can be

sketched accurately enough by noting that the amplitude ratio at the corner frequency is  $Q = 1/2\zeta = 2.5$ . The low- and high-frequency phase asymptotes are  $0^\circ$  and  $-180^\circ$  respectively. The mid-frequency asymptote passes through  $-90^\circ$  at the undamped natural frequency  $\omega_n = 10$  rad/s.

- we then simply add the separate curves to get the amplitude ratio and phase curves for the complete system:

